

# AG-440B/AG-445B CAPSTAN SERVO KIT

INSTALLATION OPERATION

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	Installation and Operation Manual 4890319-02		**************************************
REASON FOR	ERRATA To correct oscilloscope Test Point	Reference i	n Gain Adjustment
	Procedure		

Page Reference	Nature of Errata
13	Step 2: Connect scope probe to Test Point 2 of the capstan servo PWA instead of to pin 6.

Sheet \_\_1\_ of \_\_1\_

# AG-440B/AG-445B CAPSTAN SERVO KIT

# INSTALLATION OPERATION

# AMPEX CORPORATION AUDIO-VIDEO SYSTEMS DIVISION

# Prepared by

Audio-Video Technical Publications MS 22-03

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### **GENERAL INFORMATION**

This manual is a supplement to be used in conjunction with the basic Ampex AG-440B and AG-445B Recorder and Reproducer manual 4890301-03. Supplementary information in this publication describes installation and operation of the AG-440B/AG-445B Capstan Servo Kit, catalog number 4859145. The kit comprises the following main components:

- 1. Capstan motor/tachometer, part number 4020352.
- 2. Servo chassis assembly, part number 4020362-02.
- 3. Take-up idler arm.
- 4. Capstan dust cover.

The function of the capstan servo kit is to improve transport performance by making tape speed entirely independent of power line voltage and frequency variations. The kit also expands the number of tape speed pairs which can be assigned to the existing high/low tape SPEED switch. That is, the two-position tape SPEED switch can be connected, by means of jumpers, to select any two of the following four standard tape speeds: 3.75 in/s, 7.5 in/s, 15 in/s and 30 in/s. Tape speed can also be controlled externally over the range of 3.00 in/s to 45 in/s by means of an external reference signal source. Refer to the maintenance section for details regarding both internal and external tape speed selection.

When used in conjunction with the AG-440B/AG-445B Sync-Lock Kit (catalog number 4020391), the capstan servo kit also permits capstan speed synchronization with a control track or standard pilot tone signal.

Table 1 lists specifications for the modified AG-440B/AG-445B. Because of possible design improvements or equipment modifications, all specifications are subject to change without notification.

Table 1. Modified AG-440B/AG-445B Specifications

PARAMETER	SPECIFICATIONS										
Tape Speeds	3.75 in/s, 7.5 in/s, 15 in/s, and 30 in/s in speed pairs										
Start-up Time	0.1 second to operating speed 3.0 seconds to flutter specifications										
Flutter		Weighted DIN	Unweighted NAB								
	30 in/s	0.06%	0.05%								
	15 in/s	0.06%	0.06%								
	7.5 in/s	0.08%	0.08%								
	3.75 in/s 0.1% 0.1										
Tape Speed Accuracy	±0.08% from	beginning to end of r	reel								

### INSTALLATION

Install the capstan servo kit as follows:

- 1. Loosen the transport-position retaining nut and tilt the front of the transport up to the limit of its travel. Hand tighten the transport-position retaining nut. Remove the front cover by loosening the two retaining screws.
- 2. Using a 5/64 Allen wrench, remove the capstan idler from the idler arm.
- 3. Remove the dust cover from the capstan. See Figure 1.
- 4. Supporting the weight of the capstan motor, remove the four retaining screws from the top side of the transport plate. Carefully remove the capstan motor and hum shield.
- 5. Remove the capstan motor capacitor from the underside of the transport casting. Refer to Figure 2.
- 6. Loosen the transport-position retaining nut and tilt the transport back down to the horizontal position. Hand tighten the retaining nut.
- 7. On some machines it is necessary to enlarge the hole in the transport plate occupied by the capstan motor. Check the size of the hole in the machine against the size required by the dc capstan motor included in the kit.
- 8. If necessary, the capstan hole can be enlarged by using the supplied template and a half-round file. Care must be exercised to ensure that the enlarged hole remains centered with respect to the four mounting screws.

#### CAUTION

DURING THE FILING OF THE TRANSPORT PLATE, BE SURE THAT NO METAL PARTICLES ENTER ANY OF THE ELECTRONIC OR MECHANICAL COMPONENTS INSIDE THE MACHINE. FAILURE TO HEED THIS WARNING MAY RESULT IN SERIOUS DAMAGE TO THE EQUIPMENT.

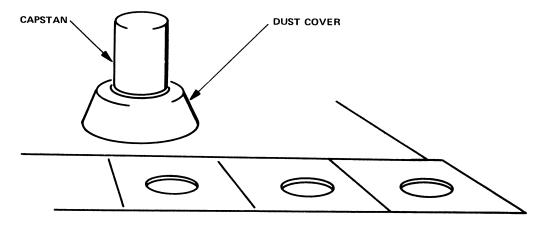


Figure 1. Dust Cover Position

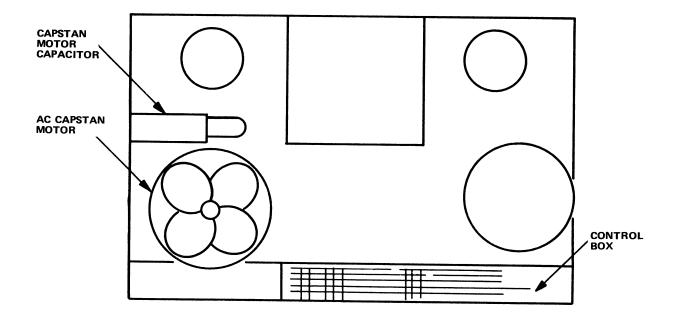


Figure 2. Underside of Transport Assembly

- 9. Loosen the transport-position retaining nut and tilt the front of the transport to the limit of its travel. Hand tighten the transport-position retaining nut.
- 10. Install the new dc capstan motor (part number 4020352, version -02 for the one-half inch capstan, version -03 for the one-inch capstan) with its tachometer pickup side toward the take-up reel. Install and tighten the four retaining screws.

- 11. Install the capstan servo chassis included with the kit (part number 4020362-01) on the rear panel of the AG-440B/445B as shown in Figure 3. Use the hardware supplied. The precise location of the servo chassis on the rear panel is not critical.
- 12. Thread the cable assembly from the previously installed dc capstan motor through the opening in the rear panel of the AG-440B/445B and connect to J6 on the servo chassis as shown in Figure 3.
- 13. Thread the cable assembly emerging from the servo chassis through the opening in the rear panel of the AG-440B/445B and mate the connector with the jack designated CAPSTAN MOTOR on the control box. Connect the two knife disconnects to the correspondingly colored leads originally connected to the capstan motor capacitor.
- 14. In the rear and underside portions of the machine, use the supplied nylon tie-wraps to dress the cables away from the motors, and to relieve any strain.
- 15. Replace the front cover initially removed in step 1. Return the transport to the horizontal position and hand tighten the transport-position retaining nut.
- 16. Replace the capstan idler on the idler arm.
- 17. Place the round aluminum dust cover on the capstan bearing support as shown in Figure 1.
- 18. Obtain the dummy plug from the kit and install into J4 on the lower side of the servo chassis previously mounted on the rear panel of the machine.
- 19. Readjust capstan idler pressure as described in AG-440 manual.

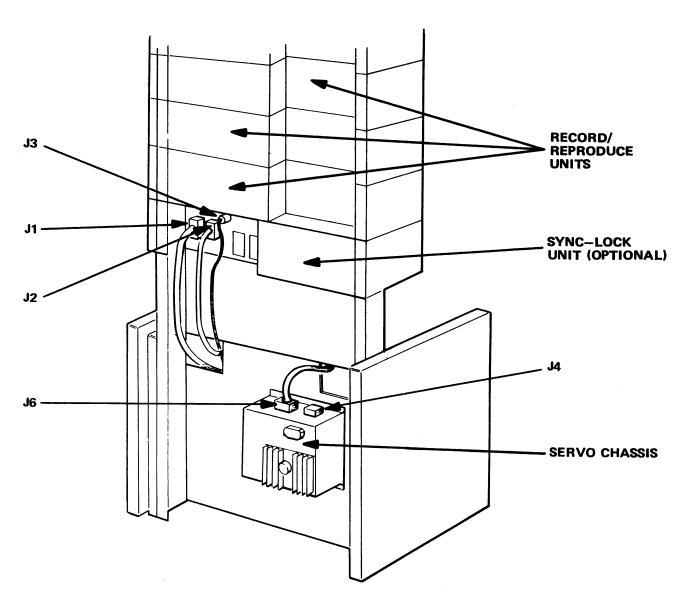


Figure 3. Servo Chassis Location

# THEORY OF OPERATION

The capstan servo system uses a high torque, direct drive, dc motor which employs a closed-loop servo for speed control. The servo system provides four tape speeds, which may be strapped in pairs to the SPEED switch on the transport control panel. The kit consists of a dc power supply, a motor drive amplifier, a dc capstan motor with tachometer, a reference oscillator, a selectable frequency divider, a phase comparator, and a low-pass filter. Except for the dc power supply and the dc capstan motor, all electronic circuitry is contained on a printed wiring assembly mounted inside the servo chassis.

The servo drive system operates on the output of the dc power supply. Direct speed control of the dc capstan motor is provided by the motor drive amplifier, which regulates the supply of dc power to the motor in accordance with servo requirements to maintain precise capstan speed.

During operation of the AG-440B or AG-445B with the servo kit, tachometer pulses are provided at a rate proportional to capstan speed. As shown in Figure 4, the tachometer pulses are amplified and fed to a digital phase comparator. The other input to the phase comparator is provided by the reference oscillator, the output of which is divided down to the frequency required to obtain the desired capstan speed. The tachometer pulses are compared with the selected reference frequency, and any frequency difference between them causes the comparator to produce a corresponding output voltage. If the capstan motor slows down for any reason, the output of the phase comparator causes the motor drive amplifier to provide more current to the capstan motor. This servo action increases the speed of the capstan to help compensate for the slowdown. Conversely, if the capstan motor speeds up, the phase comparator causes a slow-down of the motor accordingly. In this manner, small variations in capstan speed are overcome.

When a different tape speed is selected, a large change in the selected reference frequency applied to the phase comparator results. For example, if operation is taking place at a selected tape speed of 7.5 in/s, and a new speed of 3.75 in/s is selected on the SPEED switch, the reference input to the phase comparator changes from 2400 Hz to 1200 Hz. This causes the output of the phase comparator to produce a minimum dc level to the integrating amplifier and motor drive amplifier. As a result, the capstan motor slows down.

As the capstan speed approaches 3.75 in/s, the phase comparator produces a series of pulses whose width is proportional to the phase difference between the tachometer pulses and reference frequency. The capstan continues to slow down until the pulses from the phase comparator have a 20% duty cycle. (This permits a greater amount of corrective torque in the positive, or "speed up" condition.) At this time, sufficient motor drive current is maintained to cause a capstan speed of 3.75 in/s. Again, any variation in capstan speed is detected by the phase comparator, which in conjunction with the integrating amplifier, brings about the corrective change in capstan drive current to maintain proper tape speed.

The reference oscillator and divider is crystal-controlled and produces a 9600-Hz square-wave output to the selectable frequency divider network. The divider provides division of the reference frequency by factors of 2, 4, and 8 as selected by the strapping arrangement in conjunction with the SPEED switch. If the 30-in/s tape speed is selected, the output of the reference oscillator is fed undivided (shown in Figure 4 as divided by one) to the phase comparator. If the capstan is not turning at the 30-in/s rate, there will be a significant frequency difference between the 9600-Hz output of the reference oscillator and the tachometer pulses. As a result, a significant error voltage is developed which causes an increase in the motor drive amplifier output, causing the capstan to speed up until the tachometer pulses are synchronous with the reference oscillator output.

When a lower capstan speed is selected, the reference oscillator is divided by a factor of 2, 4, or 8, depending upon which tape speed is selected. Since the reference frequency is now lower than that of the tachometer output, the error voltage developed by the phase comparator and integrating amplifier causes the motor drive amplifier to reduce its output to the capstan motor. This action causes the capstan motor to slow down to the selected tape speed where the phase comparator in conjunction with the integrating amplifier produces the amount of control voltage necessary to maintain the proper speed of the capstan.

The servo operates in a similar manner when the reference oscillator is replaced with an external square-wave generator. That is, the capstan motor will be caused to adjust its speed so that the tachometer pulses are synchronous with the externally-generated reference frequency.

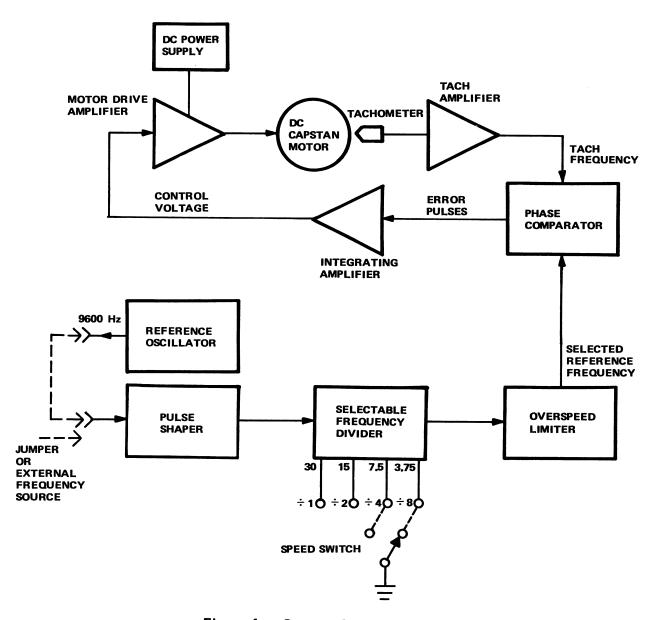


Figure 4. Capstan Servo Block Diagram

#### **OPERATION**

#### SPEED PAIR SELECTION

The front panel SPEED switch on the AG-440B and AG-445B permits the selection of the high or low operating speed. The assignment of the high and low operating speeds is determined by a strapping arrangement on the servo printed wiring assembly. Selected tape operating speeds may be any two of the following: 30 in/s, 15 in/s, 7.5 in/s and 3.75 in/s. Strap the speed pair as follows:

- 1. On the transport control panel, set the switch to OFF.
- 2. Slide the servo printed wiring assembly out of the servo chassis.
- 3. Connect a jumper from the terminal associated with the low position of the SPEED switch, designated E2, to the terminal associated with the desired low tape speed (E1, E3 or E4). Refer to Figure 5.
- 4. Connect a jumper from the terminal associated with the high position of the SPEED switch, designated E5, to the terminal associated with the desired high tape speed (E3, E4 or E6).
- 5. Replace the servo printed wiring assembly in the servo chassis, component side rearward (i.e., facing away from the AG-440B/445B).

#### VARIABLE TAPE SPEED MODE

The use of the dummy plug in J4 of the servo chassis causes the capstan servo to operate with a fixed reference frequency of 9.6 kHz. To operate the system at variable tape speeds, remove the dummy plug from J4 and connect a sine or squarewave generator having an output of 3 to 30 vrms across pins 2 and 3 (ground) of a similar plug. Refer to Figure 6.

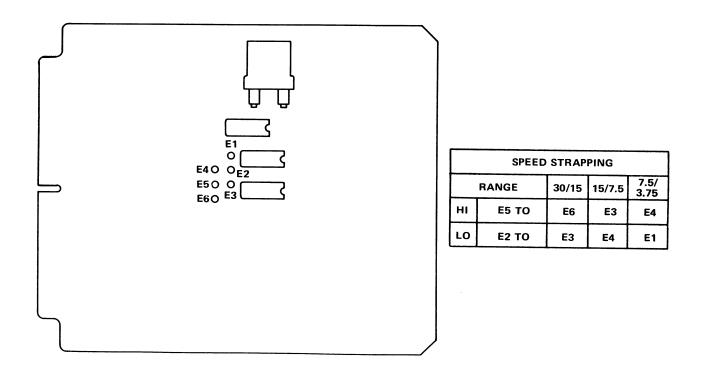


Figure 5. Tape Speed Pan Strapping

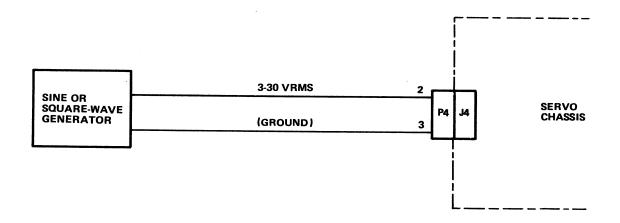


Figure 6. Connection of Square-wave Generator

Insert the new plug into J4 on the servo chassis. If a similar plug is not available, the dummy plug can be modified by removing the existing jumper between pins 1 and 4 and connecting the generator as described above. Once connected, the frequency of the generator can be used to control the speed of the tape in accordance with the values given in Table 2.

Table 2. Tape Speeds for Various Reference Frequency Inputs

TAPE SPEED (IN/S)	INPUT FREQUENCY
3.75	1200
7.5	2400
15	4800
30	9600

#### NOTE

The values given in Table 2 are with the SPEED switch in the "high" position and jumper set for 30 in/s.

#### GAIN ADJUSTMENT

This adjustment should be made only when a change in major components of the capstan servo system makes it necessary.

- 1. Put the capstan-servo PWA on extender PWA 4050695.
- 2. Attach a scope probe to pin 6 of the capstan servo PWA.
- 3. Put recorder in Play.
- 4. Adjust R19 on capstan servo PWA for minimum signal jitter.

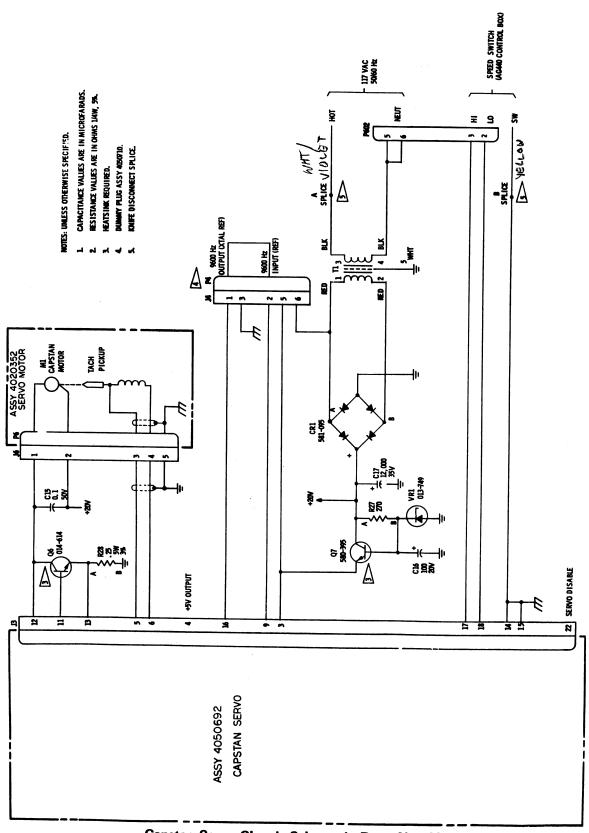
# PARTS LISTS AND SCHEMATIC DIAGRAMS

TITLE	DRAWING NO.	PAGE NO.
Capstan Servo Kit	4850145B	15
Schematic, Capstan Servo Chassis	4840355A	16
Dummy Plug Assembly, Remote Control	4050710—	17
Chassis Assembly, Capstan Servo	4020362B	18
Cable Assembly, Power	4050664—	19
Capstan Servo PWA	4050692B	20
Schematic, Capstan Servo PWA	4840356—	22

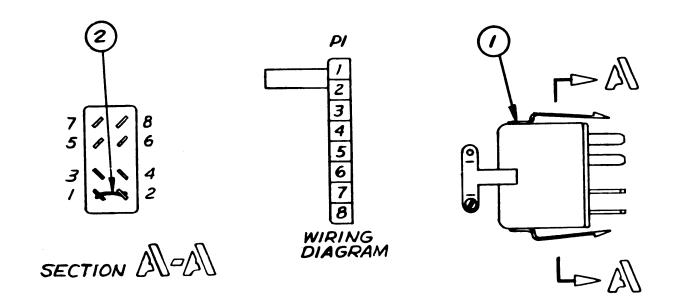
## NUMERICAL INDEX

DRAWING NO.	TITLE	PAGE NO.
4020362B	Chassis Assembly, Capstan Servo	18
4050664—	Cable Assembly, Power	19
4050692B	Capstan Servo PWA	20
4050710—	Dummy Plug Assembly, Remote Control	17
4840355A	Schematic, Capstan Servo Chassis	16
4840356	Schematic, Capstan Servo PWA	22

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Capstan Servo Chassis Schematic Dwg. No. 4840355A Ref. Assy. No. 4850145

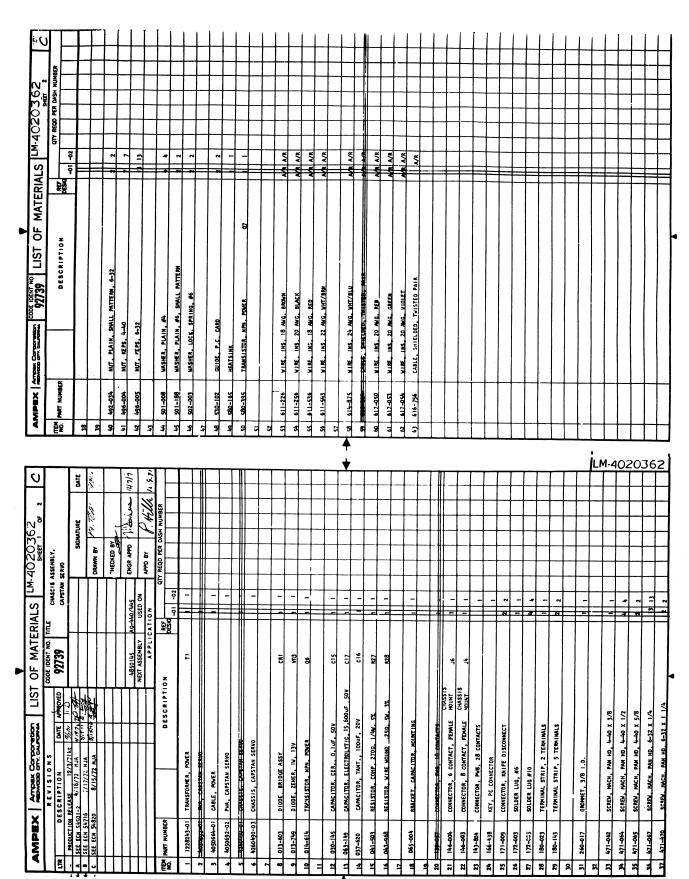


#### NOTES:

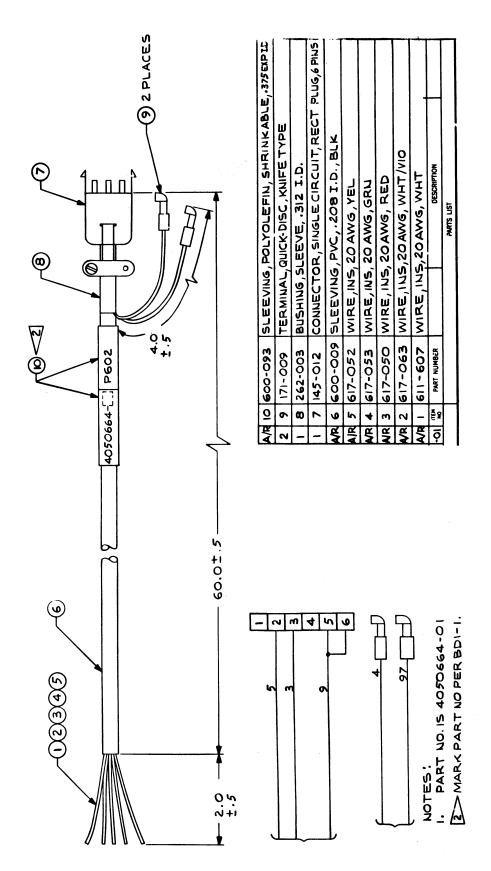
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- 2. MARK PART NO. PER BDI-1.

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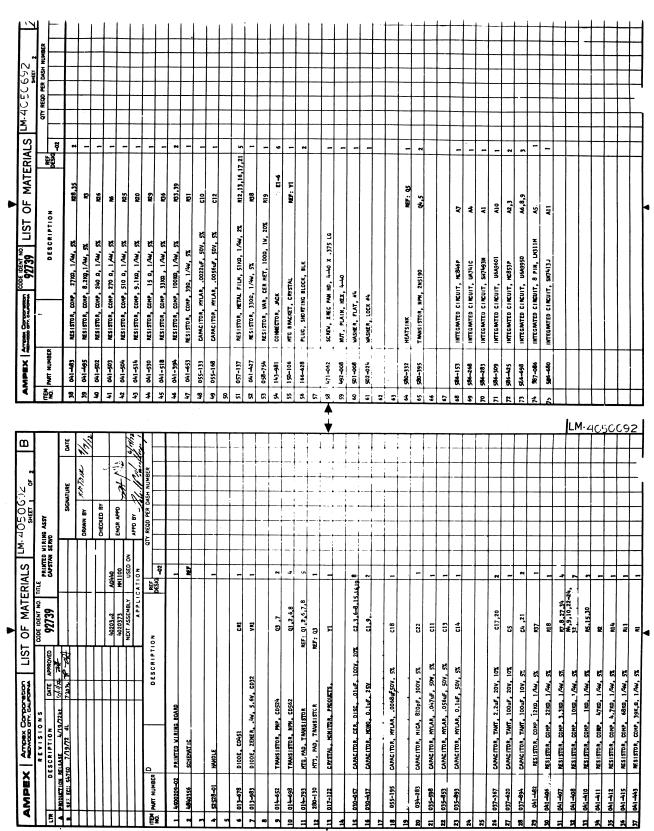
Remote Control Dummy Plug Assembly Dwg. No. 4050710-Next Assy. No. 4850145



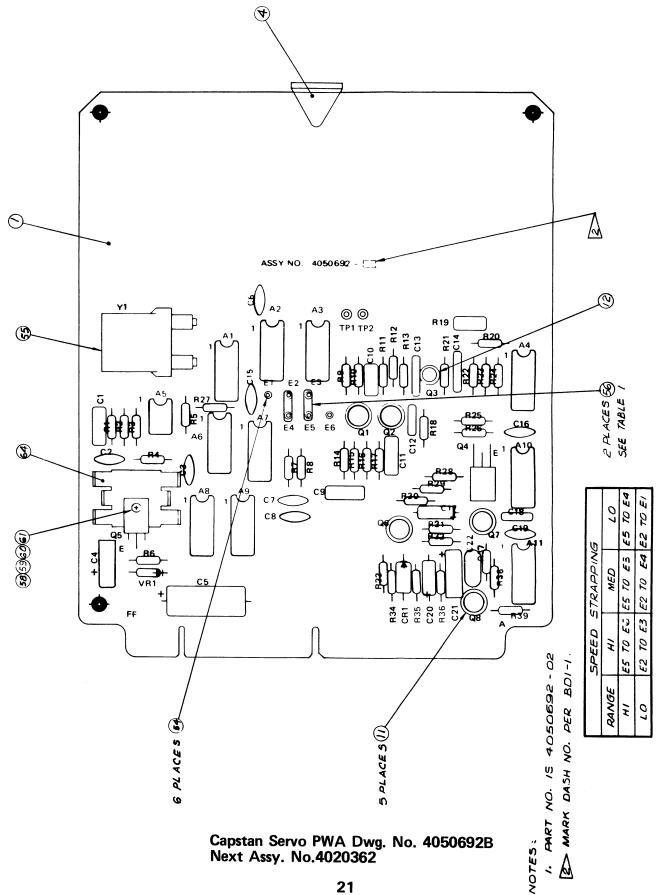
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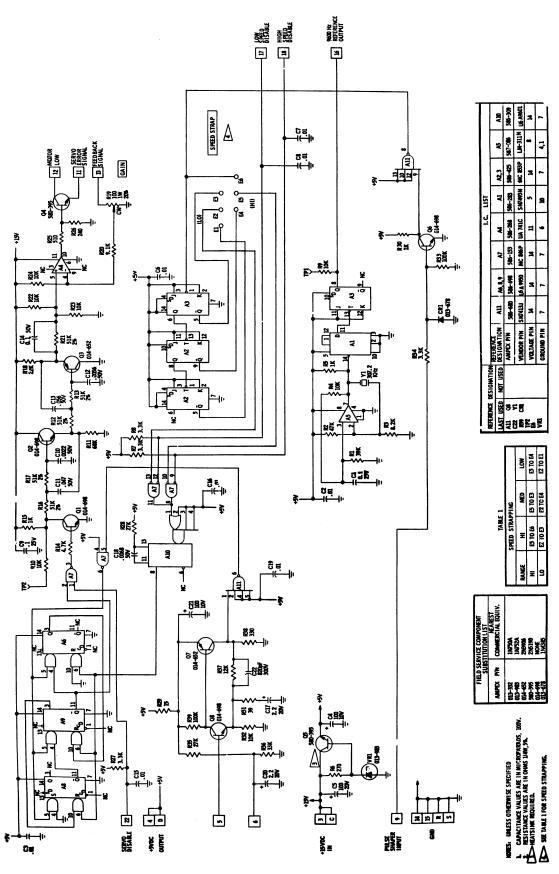


Power Cable Assembly Dwg. No..4050664-Next Assy. No. 4020362



Capstan Servo PWA LM No. 4050692B Next Assy: 4020362





Capstan Servo PWA Schematic Dwg. No. 4840356 Ref. Assy. No. 4050692